## Physics 11 Homework IV Solutions

Ch. 4 - Problems 6, 11, 16, 20, 30, 36, 37, 58, 62, 65.

## Problem 6

We have the following information:

$$
\begin{aligned}
m & =1.5 e 7 \mathrm{~kg} \\
F & =7.5 e 5 \mathrm{~N} \\
v_{0} & =0 \frac{\mathrm{~m}}{\mathrm{~s}}, \\
v_{f} & =\left(80 \frac{\mathrm{~km}}{\mathrm{~h}}\right)\left(\frac{1000 \mathrm{~m}}{1 \mathrm{~km}}\right)\left(\frac{1 \mathrm{~h}}{3600 \mathrm{~s}}\right)=22.2 \frac{\mathrm{~m}}{\mathrm{~s}} .
\end{aligned}
$$

The acceleration is given by

$$
a=\frac{F}{m}=\frac{7.5 e 5 \mathrm{~N}}{1.5 e 7 \mathrm{~kg}}=0.05 \frac{\mathrm{~m}}{\mathrm{~s}^{2}} .
$$

Using the equation $\mathrm{v}_{f}=\mathrm{v}_{0}+$ at, the time it takes to reach final velocity is

$$
t=\frac{v_{f}}{a}=\frac{22.2 \frac{m}{s}}{0.05 \frac{m}{s^{2}}}=444 \mathrm{~s} .
$$

## Problem 11

We have the following information:

$$
\begin{aligned}
\vec{F}_{p} & =2000 \mathrm{~N} \hat{\mathbf{x}}, \\
\vec{F}_{r} & =-1800 \mathrm{~N} \hat{\mathbf{x}}, \\
m & =1000 \mathrm{~kg} .
\end{aligned}
$$

(a) The acceleration is given by

$$
a=\frac{\sum \vec{F}}{m}=\frac{200 \mathrm{~N}}{1000 \mathrm{~kg}}=0.2 \frac{\mathrm{~m}}{\mathrm{~s}^{2}} .
$$

(b) Assume $\mathrm{v}_{0}=0$ and $\mathrm{t}=10 \mathrm{~s}$. How far does the boat travel in this time interval?

$$
x=\frac{1}{2} a t^{2}=\frac{1}{2}\left(0.2 \frac{m}{s^{2}}\right)(10 \mathrm{~s})^{2}=10 \mathrm{~m} .
$$

(c) What is its velocity at the end of this time interval?

$$
v_{f}=a t=\left(0.2 \frac{\mathrm{~m}}{\mathrm{~s}^{2}}\right)(10 \mathrm{~s})=2 \frac{\mathrm{~m}}{\mathrm{~s}}
$$

## Problem 16

The free-body diagram appears below.


Our force equations are as follows.

$$
\begin{array}{ll}
\sum \vec{F}_{x}: & F_{1} \cos (40)-F_{2} \cos (40) \rightarrow F_{1}=F_{2} \equiv F \\
\sum \vec{F}_{y}: & 2 F \sin (40)-W=0 \rightarrow F=\frac{W}{2 \sin (40)}=\frac{100}{2 \sin (40)}=77.8 \mathrm{~N}
\end{array}
$$

## Problem 20

The free-body diagram appears below.
This problem is the same as the previous one. If the boat moves with constant velocity, the acceleration is zero which implies that the sum of the forces is as well. Thus, we find that

$$
F=2(600) \cos (30)=1039 \mathrm{~N} .
$$



Problem 20

## Problem 30

The free-body diagram appears below.


The relevant forces equation are:

$$
\begin{aligned}
N-W & =0 \\
m_{2} g-T & =m_{2} a \\
T & =m_{1} a
\end{aligned}
$$

Summing the last two equations and solving for a yields

$$
\begin{aligned}
m_{2} g & =\left(m_{1}+m_{2}\right) a \\
a & =\frac{m_{2}}{m_{1}+m_{2}} g
\end{aligned}
$$

Note that the acceleration is the same for both masses $m_{1}$ and $m_{2}$ since they are connected by cord which we assume to be ideal, i.e. massless and
inextensible. Substituting our expression for a into our second force equation above gives T as:

$$
T=m_{1} a=\frac{m_{1} m_{2}}{m_{1}+m_{2}} g
$$

## Problem 36

(a) The free-body diagram appears below.


Now, if we consider the forces acting on mass $m_{1}$, we find:

$$
\begin{array}{ll}
\sum \vec{F}_{y}: & N-W=0 \rightarrow N=m_{1} g \\
\sum \vec{F}_{x}: & T-\mu_{s} m_{1} g=m_{1} a
\end{array}
$$

Careful examination of this equation and comparison to the corresponding equations in the previous problem reveals that the block system only moves if $\mathrm{f}_{s}<\mathrm{T}$, where $\mathrm{f}_{s}=\mu_{s} m_{1} \mathrm{~g}$. If we were to write the force equation for mass $\mathrm{m}_{2}$,

$$
m_{2} g-T=m_{2} a,
$$

and solve this together with the force equations for mass $\mathrm{m}_{1}$ for the acceleration and tension, we would find,

$$
\begin{aligned}
m_{2} g-\mu_{s} m_{1} g & =\left(m_{1}+m_{2}\right) a \\
a & =\frac{m_{2}-\mu_{s} m_{1}}{m_{1}+m_{2}} g
\end{aligned}
$$

and

$$
\begin{aligned}
T & =m_{1}\left(\mu_{s} g+a\right), \\
& =m_{1} g\left(\mu_{s}+\frac{m_{2} \mu_{s} m_{1}}{m_{1}+m_{2}}\right), \\
& =m_{1} g\left(\frac{m_{1} \mu_{s}+m_{2} \mu_{s}+m_{2}-m_{1} \mu_{s}}{m_{1}+m_{2}}\right), \\
& =\frac{m_{1} m_{2}}{m_{1}+m_{2}}\left(1+\mu_{s}\right) g .
\end{aligned}
$$

So, in order for the system to begin moving, we must have

$$
\begin{aligned}
T & >f_{s}, \\
\frac{m_{1} m_{2}}{m_{1}+m_{2}}\left(1+\mu_{s}\right) g & >\mu_{s} m_{1} g, \text { or } \\
\frac{m_{2}}{m_{1}+m_{2}}\left(1+\mu_{s}\right) & >\mu_{s}, \\
m_{2}+m_{2} \mu_{s} & >m_{1} \mu_{s}+m_{2} \mu_{s}, \\
\mu_{s} & <\frac{m_{2}}{m_{1}} .
\end{aligned}
$$

With $\mathrm{m}_{1}=10 \mathrm{~kg}$ and $\mathrm{m}_{2}=4.0 \mathrm{~kg}$, this means that $\mu_{s}<\frac{4.0 \mathrm{~kg}}{10 \mathrm{~kg}}=0.40$. Since $\mu_{s}=0.50>0.40$, the system does not move. Alternately, plugging in the given values we find that $\mathrm{a}=-0.07 \mathrm{~g}<0$. Clearing, this result cannot be physical, as it tells us that, without an externally applied force, mass $\mathrm{m}_{2}$ moves upward against the force of gravity. (Although it might be kind of interesting to see, and if you can figure out how to do it, you will go on to fame and fortune.) Nevertheless, our everyday experience tells us this is nonsensical - the only reasonable interpretation being that the system simply does not move. However, it is a good idea to always compare the forces as we did above.
(b) The free-body diagram is the same as in part (a). With a coefficient of kinetic friction $\mu_{k}=0.30$ and using the expression for acceleration found above (it carries over perfectly well here, as all we have done is make the substitution $\mu_{s} \rightarrow \mu_{k}$ ), we find

$$
a=\frac{m_{2}-\mu_{s} m_{1}}{m_{1}+m_{2}} g=\frac{(4.0-(0.30)(10)) k g}{(10+4.0) k g} g \approx 0.07 g=0.7 \frac{\mathrm{~m}}{\mathrm{~s}^{2}} .
$$

## Problem 37

We have the following information:

$$
\begin{aligned}
F & =300 \mathrm{~N} \\
\theta & =20.0^{\circ} \\
W & =1000 \mathrm{~N}
\end{aligned}
$$

(a) Note that $\mathrm{v} \equiv$ constant $\rightarrow \mathrm{a}=0$. The free-body diagram appears below.


The sum of the forces in the $\hat{\mathbf{y}}$ direction yields

$$
\begin{aligned}
0 & =N-W-F \sin (\theta) \\
N & =W+F \sin (\theta) \\
& =1000+300 \sin (20), \\
& =1103 N .
\end{aligned}
$$

The sum of the forces in the $\hat{\mathbf{x}}$ direction yields

$$
\begin{aligned}
0 & =F \cos (\theta)-\mu_{s} N, \\
\mu_{s} & =\frac{F \cos (\theta)}{N}, \\
& =\frac{300 \cos (20)}{1000+300 \sin (20)}, \\
& =0.256
\end{aligned}
$$

(b) The free-body diagram appears below.


The sum of the forces in the $\hat{\mathbf{y}}$ direction yields

$$
\begin{aligned}
0 & =N-W+F \sin (\theta), \\
N & =W-F \sin (\theta) \\
& =1000-300 \sin (20), \\
& =897 N .
\end{aligned}
$$

The sum of the forces in the $\hat{\mathbf{x}}$ direction yields

$$
\begin{aligned}
m a & =\frac{W}{g} a=F \cos (\theta)-\mu_{s} N \\
a & =\frac{g}{W}\left(F \cos (\theta)-\mu_{s} N\right) \\
& =\frac{9.8}{1000}(300 \cos (20)-(0.256)(1000-300 \sin (20))), \\
& =0.511 \frac{m}{s^{2}}
\end{aligned}
$$

## Problem 58

The free-body diagram appears below.
(a) For the mass on the table, the sum of the forces in the $\hat{\mathbf{y}}$ direction yields

$$
\begin{aligned}
0 & =N-W_{t} \\
N & =W_{t}=100 N .
\end{aligned}
$$



For the same mass, the sum of the forces in the $\hat{\mathbf{x}}$ direction yields

$$
\begin{aligned}
0 & =T-f_{s}, \\
T & =f_{s},
\end{aligned}
$$

For the hanging mass, the sum of the forces in the $\hat{\mathbf{y}}$ direction yields

$$
\begin{aligned}
0 & =W_{h}-T \\
T & =W_{h}, \\
& =50.0 \mathrm{~N} .
\end{aligned}
$$

Substituting this value above we find

$$
f_{s}=T=50.0 \mathrm{~N} .
$$

(b) Recall that the force due to static friction is defined as

$$
f_{s}=\mu_{s} N .
$$

Thus, in order to ensure static equilibrium, the coefficient of static friction must be at least

$$
\mu_{s}=\frac{f_{s}}{N}=\frac{f_{s}}{W_{t}}=0.500 .
$$

(c) The coefficient of kinetic friction is $\mu_{k}=0.250$. Thus, in order for the system to move with constant speed, the total force must be zero. With the definitions found in the previous two parts, this means that

$$
\begin{aligned}
\mu_{k} W_{t} & =W_{h}, \text { or } \\
W_{h} & =(0.250)(100)=25.0 \mathrm{~N} .
\end{aligned}
$$

## Problem 62

The free-body diagram appears below.

Problem 62

(a) The force equations can be written as

$$
\begin{aligned}
5 a & =T_{1}-5.00 g \\
7 a & =7.00 g-T_{1}
\end{aligned}
$$

Solving for the acceleration yields $\mathrm{a}=\frac{g}{6}=1.63 \frac{\mathrm{~m}}{\mathrm{~s}^{2}}$.
(b) The tension $\mathrm{T}_{1}$ is easily found from above to be $\mathrm{T}_{1}=5(\mathrm{a}+\mathrm{g})=$ $\frac{35}{6} \mathrm{~g}=57.2 \mathrm{~N}$. The tension $\mathrm{T}_{2}$ is just the force acting on the 3.00 kg mass, and thus can be found easily by equating this force with the acceleration the mass experiences. Thus, $\mathrm{T}_{2}=3(\mathrm{a}+\mathrm{g})=\frac{21}{6} \mathrm{~g}=34.3 \mathrm{~N}$.

## Problem 65

The free-body diagram appears below. We have the following information:

$$
\begin{aligned}
m_{1} & =10 \mathrm{~kg} \\
m_{2} & =20 \mathrm{~kg} \\
F & =50 \mathrm{~N}
\end{aligned}
$$



Problem 65 (a)
(a) A 10 kg box is attached to a 20 kg box by an ideal string. a 50 N force is applied to the 20 kg box. As can easily be seen in the free-body diagram, the force is actually applied to the system that is both masses. Thus, acceleration of each box is the same and is given by

$$
a=\frac{F}{m}=\frac{50 \mathrm{~N}}{(10+20) k g}=1.7 \frac{\mathrm{~m}}{\mathrm{~s}^{2}} .
$$

The tension in the connecting ideal string is given by

$$
T=m_{1} a=(10 \mathrm{~kg})\left(1.67 \frac{\mathrm{~m}}{\mathrm{~s}^{2}}\right)=17 \mathrm{~N} .
$$

(b) The free-body diagram appears below.


Let's consider the same scenario, but this time there exists a coefficient of kinetic friction, $\mu_{k}=0.10$ between each box and the surface. Then, the force equation for the two box system is

$$
\begin{aligned}
\left(m_{1}+m_{2}\right) a & =50-f_{k} \\
& =50-\mu_{k}\left(m_{1}+m_{2}\right) g \\
a & =\frac{50-\mu_{k}\left(m_{1}+m_{2}\right) g}{m_{1}+m_{2}} \\
& =0.69 \frac{\mathrm{~m}}{s^{2}}
\end{aligned}
$$

The tension can be found from

$$
\begin{aligned}
m_{1} a & =T-f_{k}, \\
& =T-\mu_{k} m_{1} g, \\
T & =m_{1}(a+\mu k g), \\
& =17 N .
\end{aligned}
$$

