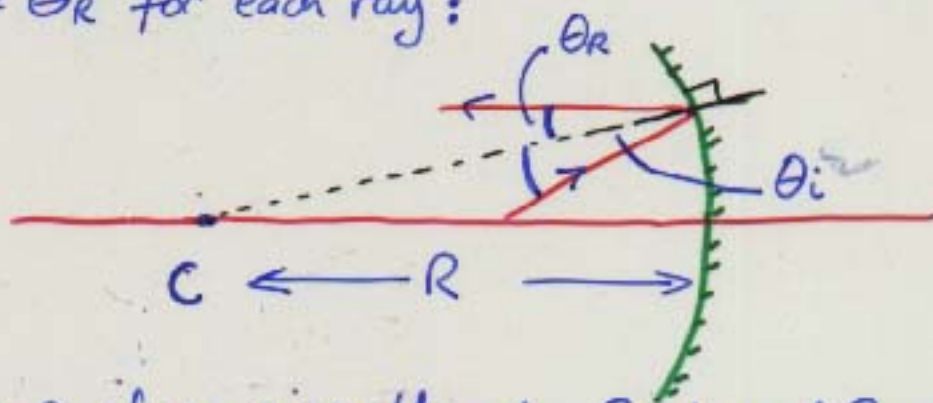


Spherical Mirrors

- Can focus rays of light close to $\frac{1}{2}$ to surface. Geometry from law of reflection $\theta_i = \theta_r$ for each ray:

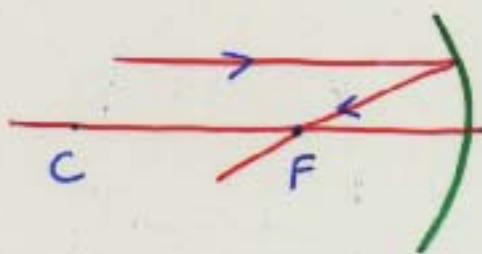


(Normal to surface passes through Center of Curvature)

From geometry, find focal length $f = -\frac{R}{2}$

Concave mirror:

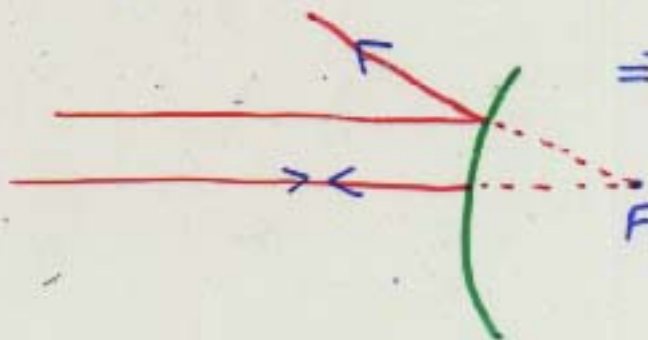
$$(R < 0)$$



$\Rightarrow$ converging
 $f > 0$

Convex mirror:

$$(R > 0)$$

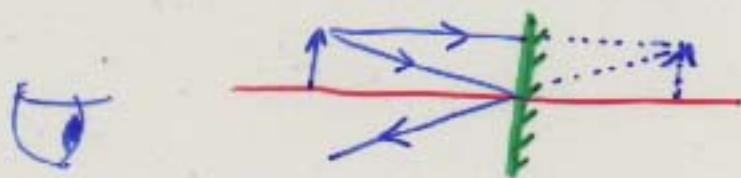


$\Rightarrow$ diverging
 $f < 0$

Mirrors

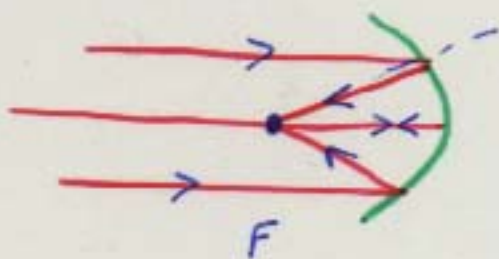
Plane mirror $\Rightarrow$ undistorted virtual image
(flipped left-right)

= special case of curved mirror with $f \rightarrow \infty$
(i.e. $\parallel$ rays remain $\parallel$).



Paraboloidal Mirrors either:

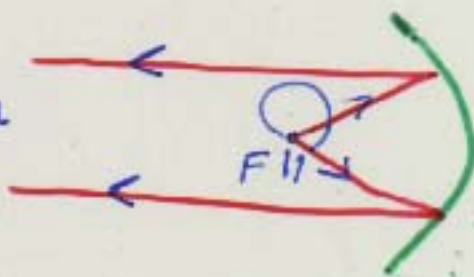
bring $\parallel$ rays to
a sharp focus F



e.g. Satellite dish

or:

produce $\parallel$ beam
from source at "F"



e.g. Search light

.. also ellipsoidal, hyperbolic mirrors

(Hecht fig. 24.33)

Finite Imagery - Ray Diagrams

We can construct images by geometry as with lenses, e.g.

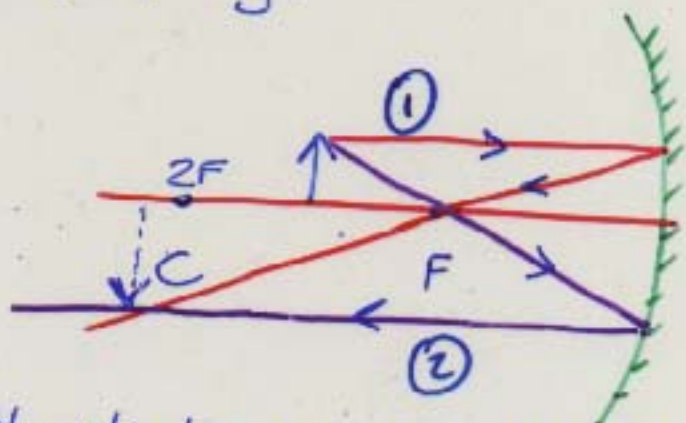
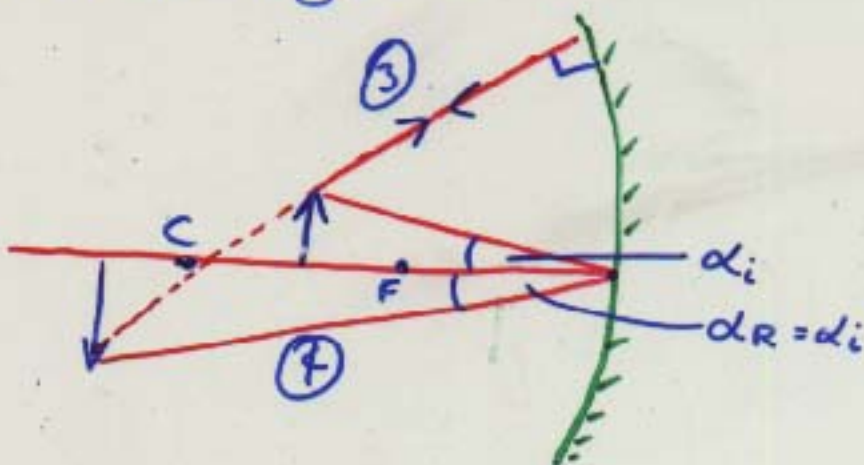


image is
real, inverted
magnified

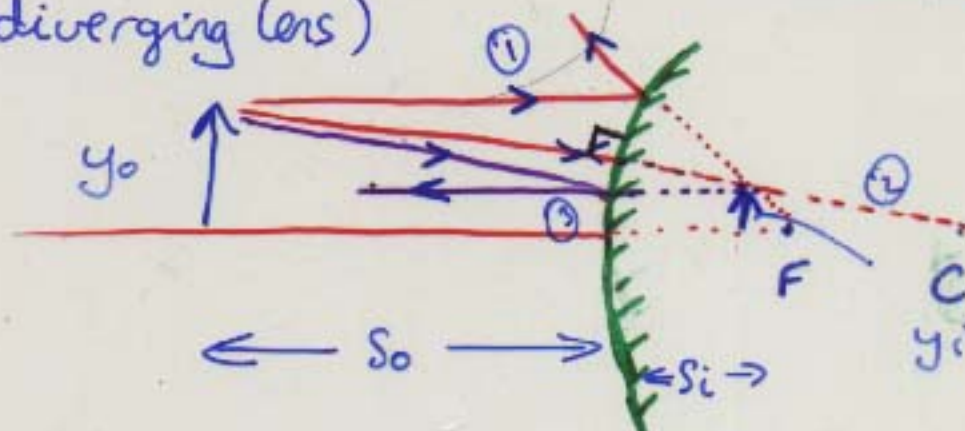
- ① ray $\parallel$ optical axis reflected through F
- ② ray through F reflected $\parallel$

Two more rays



- ③ ray through C is $\perp$ to surface - reflected straight back
- ④ ray striking mirror at $\theta = \alpha_i$, reflected at $\theta = \alpha_r$.

Convex mirror $\Rightarrow$ virtual, erect, minified image
(c.f. diverging lens)



- ① ray $\parallel$ opt. axis diverges from F
- ② ray towards C reflected straight back
- ③ ray towards F reflected $\parallel$ to opt. axis

Spherical Mirror Equation

$$\boxed{\frac{1}{S_o} + \frac{1}{S_i} = \frac{1}{f}}$$

- As for lenses, except $S_i > 0 \Rightarrow$ real image on left
 $S_i < 0 \Rightarrow$ virtual " " right.

Also, as for lenses, from similar Δ s

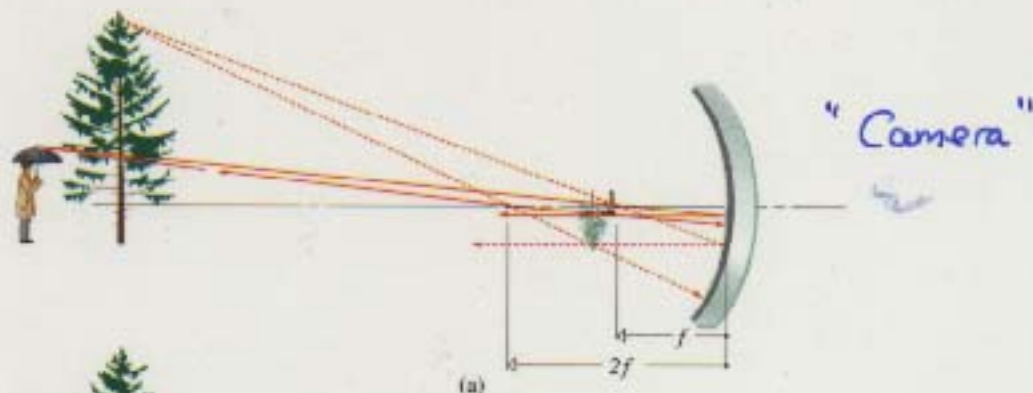
$$\frac{y_i}{y_o} \quad \boxed{M_T = \frac{-S_i}{S_o}}$$

Images Formed by a Concave Spherical Mirror

1. $s_o > 2f$

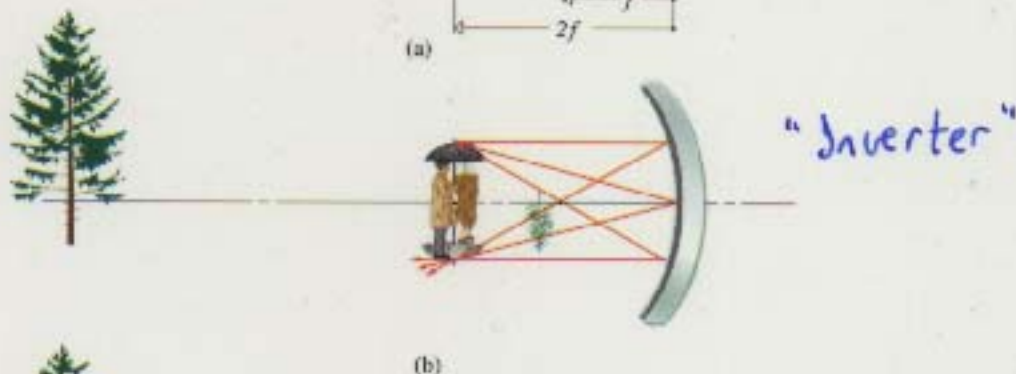
~~Magn~~

$-1 < M_T < 0$

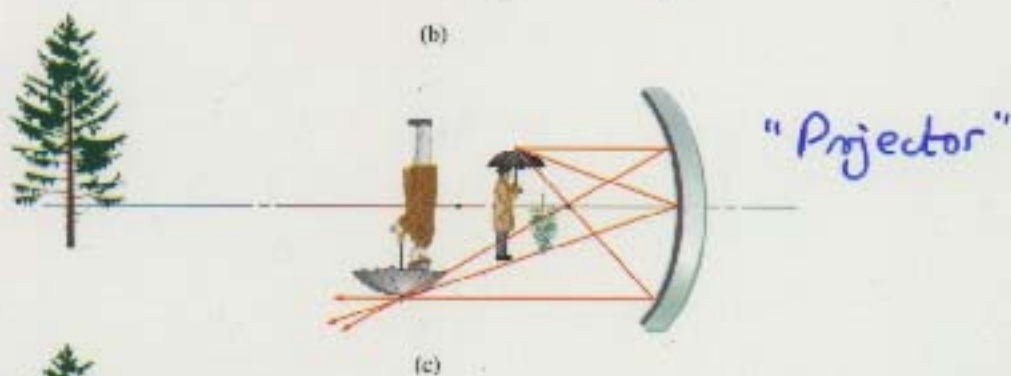


2. $s_o = s_i = 2f$

$M_T = -1$

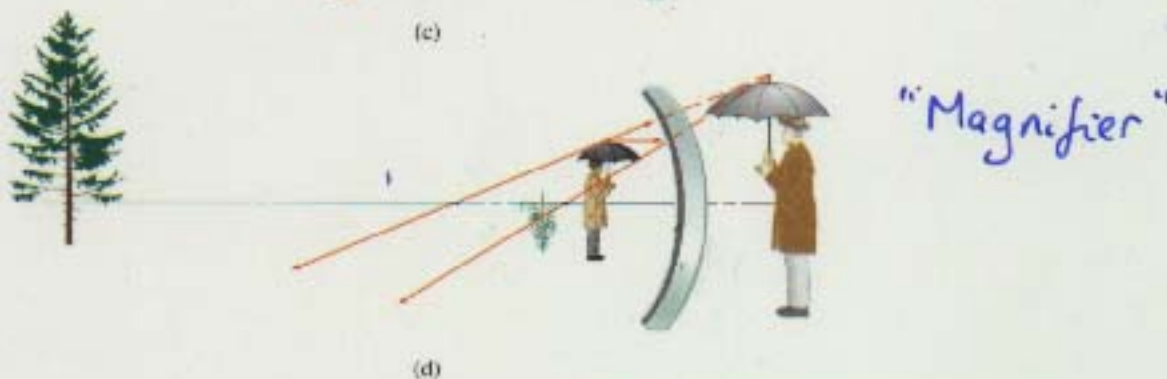


3. $f < s_o < 2f$

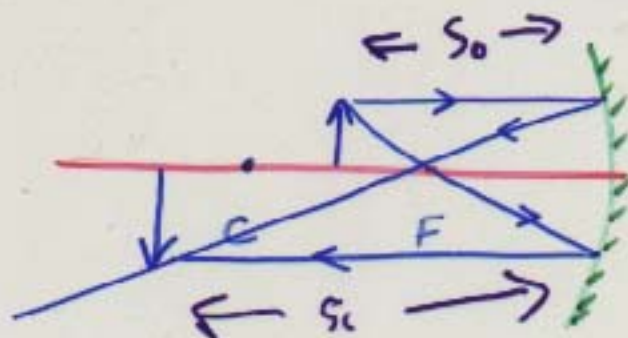


4. $s_o < f$

$M_T > +1$



Example: Use an $f = +60\text{cm}$ mirror to project
TV image onto a wall with $3\times$ magnification



We have real, inverted image with $M_T = \frac{-s_i}{s_o} = -3$

i.e. $s_i = 3s_o$

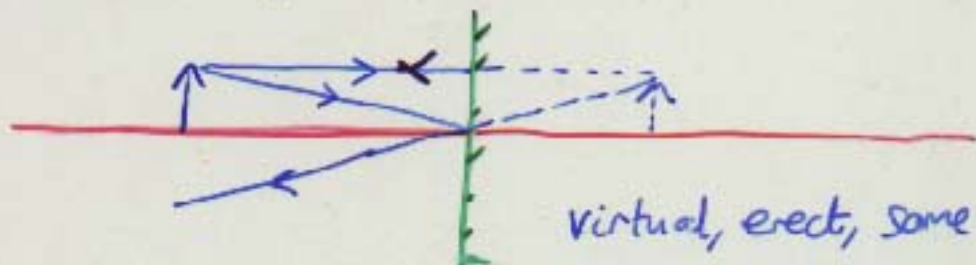
Using $\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f} \Rightarrow \frac{1}{3s_o} + \frac{1}{s_o} = \frac{1}{f}$

i.e. $\frac{3}{4} \frac{1}{s_o} = \frac{1}{f} \Rightarrow s_o = +\frac{3}{4}f = 80\text{cm}$

and image distance $s_i = 3s_o = 240\text{cm}$
 $= 4f$

- Geometry same as lens except for left-right reflection.

c.f. plane mirror ($f \rightarrow -\infty$)



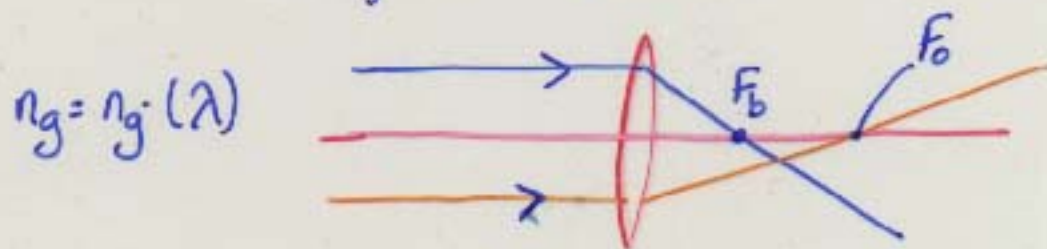
virtual, erect, same
Size $M_T = 1$

Advantages of Mirrors, Applications

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1. Easier to make - not transparent
2. Can be supported at back, not just edges
3. Achromatic : $\theta_r = \theta_i$ for all colors

c.f. lens $\frac{1}{f} = \left(\frac{n_g}{n_a} - 1 \right) \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$



- f also changes with n_a (e.g. underwater)

Applications:

Concave: headlamps, vanity/dentist's mirror

Convex: passenger-side mirror, wide-angle security mirror.